# Distributed Transactions with

#### Two-Phase Commit Alvin Cheung

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R&G - Chapter 22



## Distributed vs. Parallel?

- Earlier we discussed Parallel DBMSs
  - Shared-memory
  - Shared-disk
  - Shared-nothing
- Distributed is basically shared-nothing parallel
  - Perhaps with a slower network
    - Possibly thanks to being geographically distributed

#### What's Special About Distributed Computing?

- Inherited from shared-nothing parallel computation
  - Parallel computation
  - No shared memory/disk
- Unreliable Networks
  - Delay, reordering, loss of packets
- Unsynchronized clocks
  - Impossible to have perfect synchrony
- Partial failure: can't know what's up, what's down

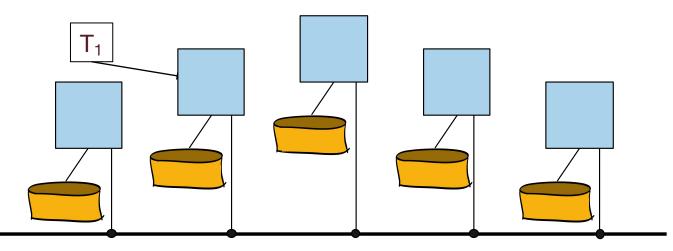
## **Distributed Database Systems**

- DBMS an influential special case of distributed computing
  - The trickiest part of distributed computing is state, i.e. Data
  - Transactions provide an influential model for concurrency/parallelism
  - DBMSs worried about fault handling early on
- Special-case because not all distributed programs are written transactionally
  - And if not, database techniques may not apply
- Many of today's most complex distributed systems are databases
  - Cloud SQL databases like Google Spanner, AWS Aurora, Azure SQL
  - NoSQL databases like DynamoDB, Cassandra, MongoDB, Couchbase...
- We'll focus on transactional concurrency control and recovery
  - You already know many lessons of distributed query processing

#### **DISTRIBUTED LOCKING**

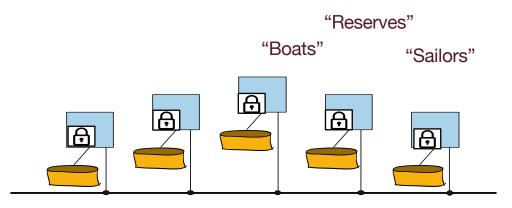
## **Distributed Concurrency Control**

- Consider a shared-nothing distributed DBMS
- For today, assume partitioning but no replication of data
- Each transaction arrives at some node:
  - The "coordinator" for the transaction
    - Can be designated or assigned on the fly



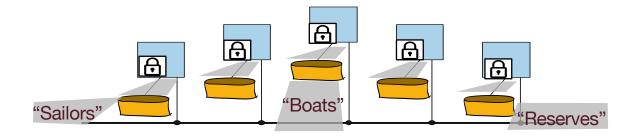
### Where is the Lock Table

- Typical design: Locks partitioned with the data
  - Independent: each node manages "its own" lock table
  - Works for objects that fit on one node (pages, tuples)
- For coarser-grained locks, assign a "home" node
  - Object being locked (table, DB) exists across nodes



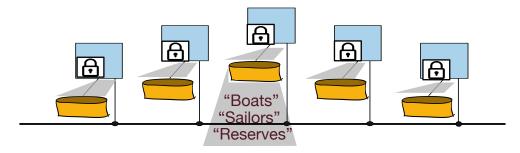
### Where is the Lock Table, Pt 2

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  - These coarse-grained locks can be partitioned across nodes



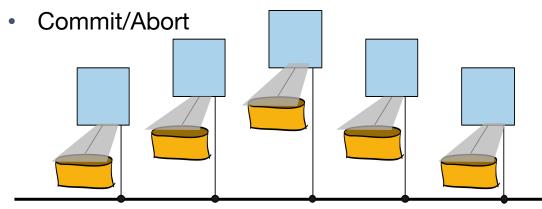
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- Typical design: Locks partitioned with the data
  - Independent: each node manages "its own" lock table
  - Works for objects that fit on one node (pages, tuples)
- For coarser-grained locks, assign a "home" node
  - Object being locked (table, DB) exists across nodes
  - These coarse-grained locks can be partitioned across nodes
  - Or centralized at a master node



#### Ignore global coarse-grained locks for a moment...

- Every node does its own locking
  - Clean and efficient
  - Nicely generalizes the single-node setting
- "Global" issues remain:
  - Deadlock

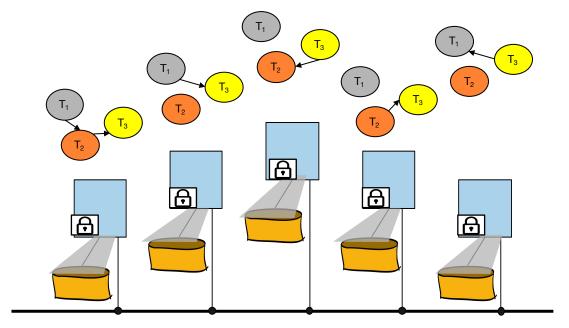


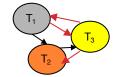
#### DISTRIBUTED DEADLOCK DETECTION

# What Could Go Wrong? #1

• Deadlock detection via waits—for graphs

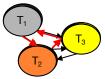
Each machine doesn't have a cycle, but there is a global cycle

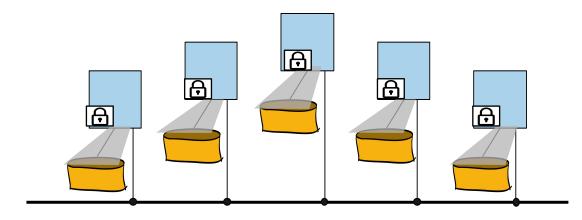




# What Could Go Wrong? #1 Part 2

- Deadlock detection via waits—for graphs
  - Easy fix: periodically union at designated coordinator

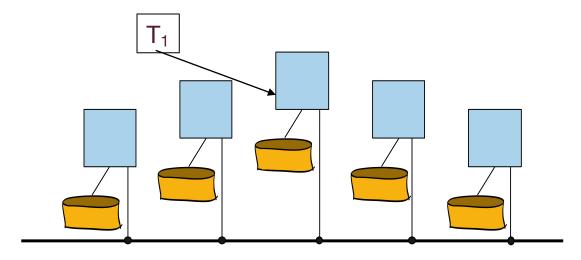




#### **DISTRIBUTED COMMIT: 2PC**

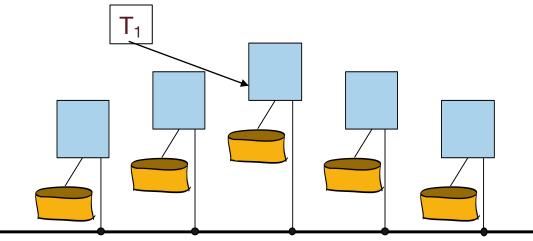
### Strawman: Coordinator makes Decision

- Recall that every txn has a coordinator node
- Coordinator decides if the txn is going to commit or abort.
- Lets all the other nodes know.
- Q: Why is this scheme problematic?



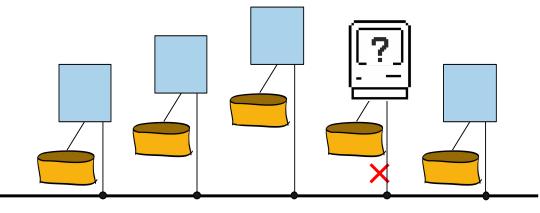
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- Recall that every txn has a coordinator node
- Coordinator decides if the txn is going to commit or abort.
- Lets all the other nodes know.
- Q: Why is this scheme problematic?
  - Among other things, one of the nodes may want to abort, even if the coordinator wants to commit
  - Some nodes may actually be down (so any txn touching their data shouldn't proceed)



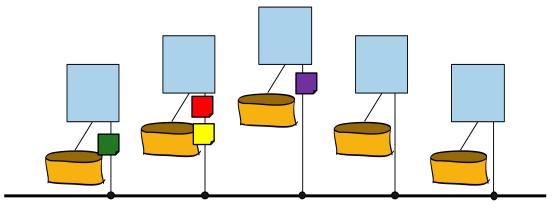
## In General, What Could Go Wrong? #2

- Failures/Delays: Nodes
  - Commit? Abort?
    - If we haven't heard from a node, we don't know if is alive or dead.
    - The decision may hinge on this node (imagine a FK violation at that node)
  - When the node comes back, how does it recover in a world that moved forward?



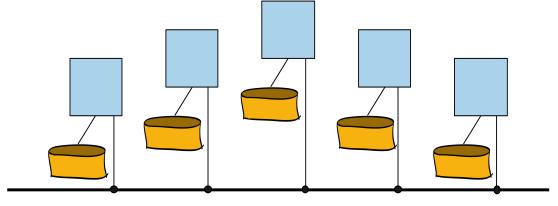
# What Could Go Wrong? #2, Part 2

- Failures/Delays: Nodes
- Failures/Delays: Messages
  - Non-deterministic reordering per channel, interleaving across channels
  - "Lost" (very delayed) messages
    - How long should we wait for this?



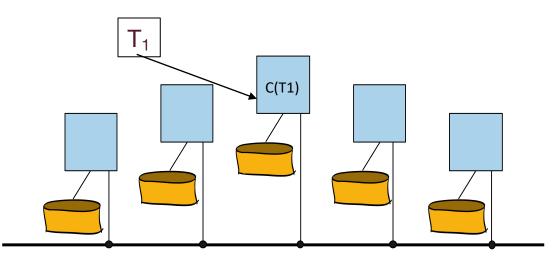
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- Failures/Delays: Nodes
- Failures/Delays: Messages
  - Non-deterministic reordering per channel, interleaving across channels
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- Given this, how do all nodes agree on Commit vs. Abort?



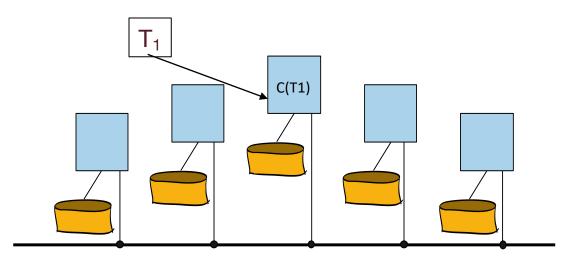
## **Basic Idea: Distributed Voting**

- Vote for Commitment
  - How many votes does a commit need to win?
  - Any single node could observe a problem (e.g. deadlock, constraint violation)
  - Hence must be unanimous.



# Distributed voting? How?

- How do we implement distributed voting?!
  - In the face of message/node failure/delay?

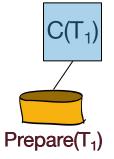


#### 2-Phase Commit

- A.k.a. 2PC. (Not to be confused with 2PL!)
- Like a wedding ceremony!
- Phase 1: "do you take this person..."
  - Coordinator tells participants to "prepare"
  - Participants respond with yes/no votes
    - Unanimity required for yes!
- Phase 2: "I now pronounce you..."
  - Coordinator disseminates result of the vote
- Need to do some logging for failure handling....

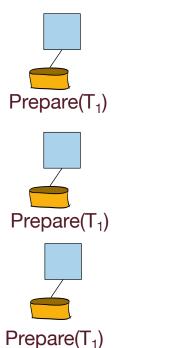
- Phase 1:
  - Coordinator tells participants to "prepare"
  - Participants respond with yes/no votes
    - Unanimity required for commit!
- Phase 2:
  - Coordinator disseminates result of the vote
  - Participants respond with Ack

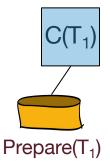




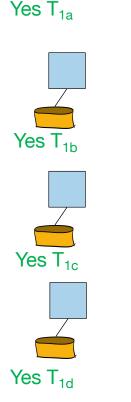
Prepare(T<sub>1</sub>)

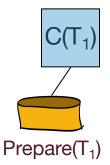
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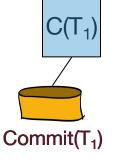






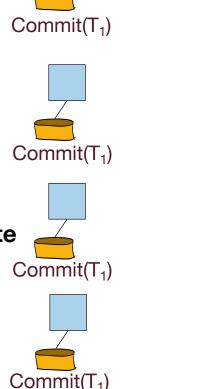
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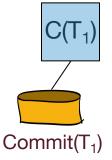




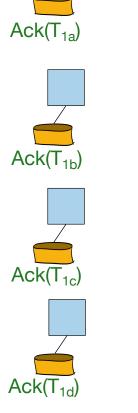


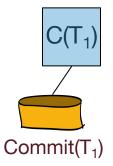
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When the coordinator receives messages from all participants, txn is complete

